# Can Testing Be Liberated From The Automata Style ???

Towards a Monadic Approach of Symbolic Behavioral Test-Generation

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#### Abstract

- Sequence Testing is an important sub-domain of formal model-based Testing. It addresses test scenarios where the tester controls the state of the System Under Test (SUT) only at the initialization time and then indirectly via a sequence of inputs. The latter may stimulate observable outputs on which the test-verdict must be based solely.
- A number of automata-based test-theories have been suggested that work fairly well for traces of impressing length provided that the state space of the SUT is small. Whenever large state spaces have to be modeled as is the case for operating systems, data-bases or web-services both theory and implementations resists obstinately practical applicability: Theoretically, because symbolic representations of state spaces have to be treated; Practically, because these difficulties result in a small number of tools addressing sparse and fairly limited application domains.
- In this talk, I will present a novel approach to the problem based on Monads, their theory developed in Isabelle/HOL. Notions like Test-Sequence and Test-Refinement can be rephrased in terms of Monads, which opens the way both for efficient symbolic execution of system models as well as the efficient compilation to test-drivers. Theoretically, the monadic approach allows to
  - 1.) resists the tendency to surrender to finitism and constructivism at the firstbest opportunity
  - 2.) provides a sensible shift from syntax to semantics: instead of a first-order, intentional view in nodes and events in automata, the heart of the calculus is on computations and their compositions

#### Overview

· HOL-TestGen and its Business-Case

· The Standard Workflow for Unit Testing

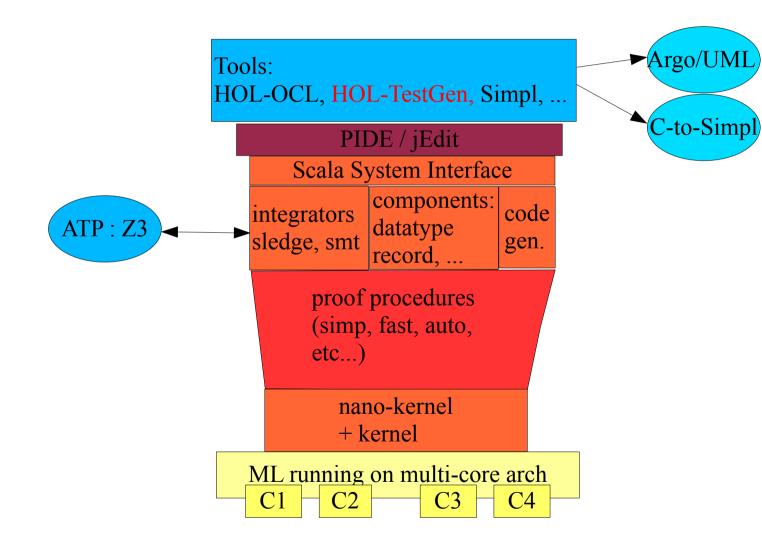
· Demo

· The Workflow for Sequence Tests

# HOL-TestGen and its Business-Case

- HOL-TestGen is somewhat unusual test-Tool:
  - implemented as "PlugIn" in a major Interactive Theorem Proving Environment: Isabelle/HOL
  - conceived as formal testcase-generation method based on symbolic execution of a model (in HOL)
  - Favors Expressivity and emphasizes Test-Plans as formal entities; emphasis on Interactivity
  - Document-centric test-development (inspired by SPECEXPLORER)

### HOL-TestGen as Plugin in the Isabelle Architecture



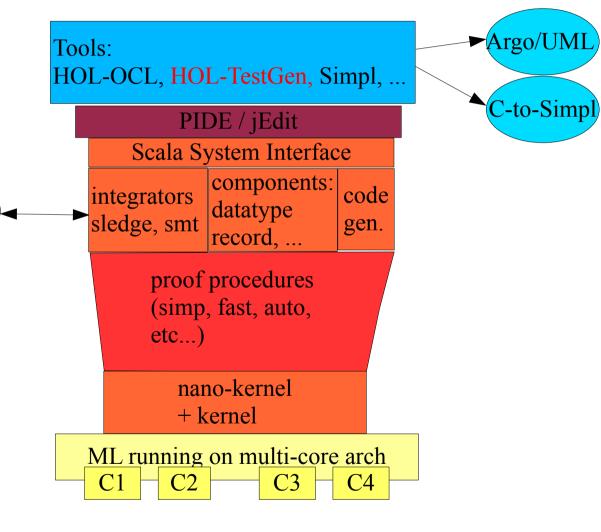
# HOL-TestGen as Plugin in the Isabelle Architecture

ATP : Z3

#### Advantage:

 Reuse of powerful components in unique, interactive integrated environment

 seamless integration of test and proof activities



#### HOL-TestGen Workflow

- Modelisation
  - writing background theory of problem domain

Writing a test-theory (the "model")

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Example: Sorting in HOL

Writing a test-theory (the "model")

Example: Sorting in HOL

- Writing a test-theory
- Writing a test-specification TS

- Writing a test-theory
- Writing a test-specification TS

```
testspec " is_sorted(PUTx)

\land asc(x, PUTx)"
```

- Writing a test-theory
- Writing a test-specification TS

pattern:

testspec "pre  $x \rightarrow post x (PUTx)$ "

- Writing a test-theory
- Writing a test-specification TS

#### example:

```
test_spec "is_sorted x \rightarrow is_sorted (PUT \ a \ x)" or test_spec "is_sorted (PUT \ l)"
```

- Writing a test-theory
- Writing a test-specification TS
- Conversion into test-theorem
   ("Testcase Generation")

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- Conversion into test-theorem
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apply(gen\_test\_cases 3 1 "PUT")

- Writing a test-theory
- Writing a test-specification TS
- Conversion into test-theorem

("Testcase Generation")

$$TC_1 \Rightarrow \ldots \Rightarrow TC_n \Rightarrow THYP(H_1) \Rightarrow \ldots \Rightarrow THYP(H_m) \Rightarrow TS$$

- where testcases  $TC_i$  have the form  $Constraint_1(x) \Rightarrow \ldots \Rightarrow Constraint_k(x) \Rightarrow P(prog \ x)$
- and where  $THYP(H_i)$  are test-hypothesis

- Writing a test-theory
- Writing a test-specification TS
- Conversion into test-theorem

#### Example:

```
is_sorted (PUT I)
1: is_sorted(PUT [])
2: is_sorted(PUT [?X])
3: THYP(∃ x. is_sorted(PUT [x]) → ∀ x. is_sorted(PUT [x]))
4: is_sorted(PUT [?X, ?Y])
```

- Writing a test-theory
- Writing a test-specification TS
- Conversion into test-theorem

```
5: THYP(∃ x y. is_sorted(PUT[x,y]) →

∀ x y. is_sorted(PUT[x,y]))

6: is_sorted(PUT [?X, ?Y, ?X])

7: THYP(∃ x y z. is_sorted(PUT [x,y,z]) →

∀ x y z. is_sorted(PUT [x,y,z]))

1.7.20158: THYP(3 < ||| ← istinsorted(PtonTh)) utomata Style?
```

- Writing a test-theory
- Writing a test-specification TS
- Conversion into test-theorem
- Generation of test-data

- Writing a test-theory
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- Conversion into test-theorem
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```
gen test data "..."
```

- Writing a test-theory
- Writing a test-specification TS
- Conversion into test-theorem
- Generation of test-data

```
is_sorted(PUT 1 [])
is_sorted(PUT 1 [0])
is_sorted(PUT 1 [2])
is_sorted(PUT 1 [1,2])
```

- Writing a test-theory
- Writing a test-specification TS
- Conversion into test-theorem
- Generation of test-data
- Generating a test-harness

- Writing a test-theory
- Writing a test-specification TS
- Conversion into test-theorem
- Generation of test-data
- Generating a test-harness
- Run of testharness and generation of test-document

#### Midi Example: Red Black Trees

Red-Black-Trees: Test Specification

where delete is the program under test.

#### HOL-TestGen Workflow

#### Demo

HOL is a state-less language;
 how to model and test stateful systems?

• How to test systems where you have only control over the initial state?

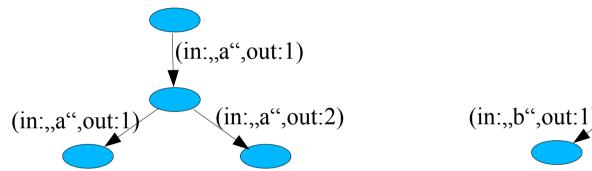
• How to test concurrent programs implementing a model?

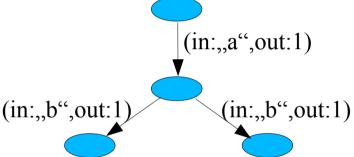
#### Testability Hypothesis in Sequence Testing

- 1. The tester can reset the system under test (the SUT) into a known initial state,
- 2. the tester can stimulate the SUT only via the operationcalls and input of a known interface; while the internal state of the SUT is hidden to the tester, the SUT is assumed to be only controlled by these stimuli, and
- 3. the SUT behaves deterministic with respect to an observed sequence of input-output pairs (it is input-output deterministic).

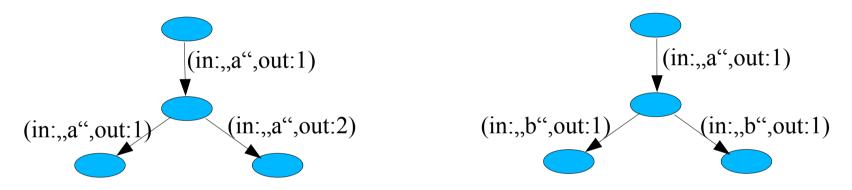
- Some notions of traditional sequence testing
  - Input-Output Automata, e.g.  $A = (\sigma, \tau :: (\sigma \times (\iota \times \sigma) \times \sigma) set)$ ,
    - σ is the type of states
    - ι the type of inputs (input events)
    - o the type of outputs (output events)
    - τ the set of input-output-transitions.

- Some notions of traditional sequence testing
  - Input-Output Automata, e.g.  $A = (\sigma, \tau :: (\sigma, (\iota, o), \sigma) set)$ ,



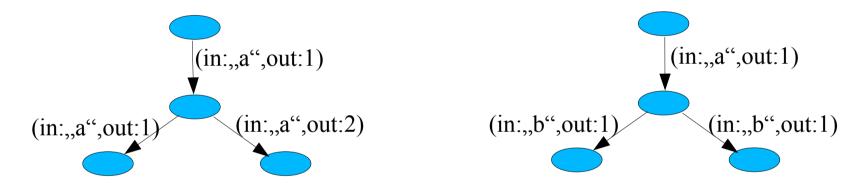


- Some notions of traditional sequence testing
  - Input-Output Automata, e.g.  $A = (\sigma, \tau :: (\sigma, (\iota, o), \sigma) set)$ ,



- $t \in Trace(A) :: (\iota, o)set$  (eg. [("a",1)("a",1)])
- set of enabled inputs after a trace:  $In_A(t)$  (eg.  $In_A([("a",1)]) = {("a")}$ )
- set of possible outputs after trace and input:  $Out_{\Delta}(t,i)$  (eg.  $Out_{\Delta}([("a",1)]) = \{1,2\})$

- Some notions of traditional sequence testing
  - Input-Output Automata, e.g.  $A = (\sigma, \tau :: (\sigma, (\iota, o), \sigma) set)$ ,



Note: IO-Determinism does NOT mean that a system is "deterministic"

- Some notions of traditional sequence testing
  - Conformance Relations assume that a model (an Automata) is refined by an implementation (assumed to be an automata)

SPEC [ IMPL

- Well-known notions are:
  - inclusion conformance[5]: all traces in SPEC must be possible in SUT,
  - deadlock conformance[7]: for all traces t ∈ Traces(SPEC) and b ∈ In(t), b must be refused by SUT, and
  - input/output conformance (IOCO)[19]: for all traces t ∈ Traces(SPEC) and all ι ∈ In(t), the observed output of SUT must be in Out(t, ι).

# How to model and test stateful systems?

- Use Monads !!!
  - The transition in an automaton  $(\sigma,(\iota, o),\sigma)$ set can isomorphically represented by:

$$\iota \Rightarrow \sigma \Rightarrow (o,\sigma)$$
 set

or for a deterministic transition function:

$$\iota \Rightarrow \sigma \Rightarrow (o,\sigma)$$
 option

... which category theorists or functional programmers would recognize as a Monad function space

# How to model and test stateful systems?

- Use Monads !!!
  - The transition in an automaton  $(\sigma,(\iota, o),\sigma)$ set can isomorphically represented by:

$$\iota \Rightarrow (o \times \sigma) \text{ Mon}_{SBE}$$
 or for a deterministic transition function:

$$\iota \Rightarrow (o \times \sigma) \text{ Mon}_{SE}$$

... which category theorists or functional programmers would recognize as a Monad function space

# How to model and test stateful systems?

- Monads must have two combination operations bind and unit enjoying three algebraic laws.
  - For the concrete case of Mon<sub>SE</sub>:

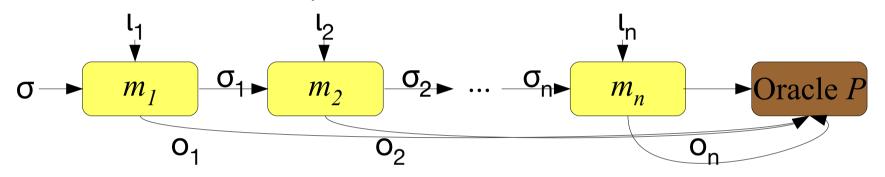
```
definition bind<sub>SE</sub> :: "('o,'\sigma)MON<sub>SE</sub> \Rightarrow('o \Rightarrow('o','\sigma)MON<sub>SE</sub>) \Rightarrow('o','\sigma)MON<sub>SE</sub>" where "bind<sub>SE</sub> f g = (\lambda \sigma. case f \sigmaof None \RightarrowNone | Some (out, \sigma') \Rightarrowg out \sigma')"

definition unit<sub>SE</sub> :: "'o \Rightarrow('o, '\sigma)MON<sub>SE</sub>" ("(return _)" 8) where "unit<sub>SE</sub> e = (\lambda \sigma. Some(e,\sigma))"
```

and write o←m; m'o for bind<sub>SE</sub> m (λo. m'o)
 and return for unit<sub>SE</sub>

# How to model and test stateful systems?

Valid Test Sequences:



- · ... can be generated to code
- ... can be symbolically executed ...

$$\overline{(\sigma \models \operatorname{return} P) = P}$$

$$\frac{C_m \iota \sigma \qquad m \iota \sigma = None}{(\sigma \models ((s \leftarrow m \iota; m' s))) = False}$$

$$\frac{C_m \iota \sigma \qquad m \iota \sigma = Some(b, \sigma')}{(\sigma \models s \leftarrow m \iota; m' s) = (\sigma' \leftarrow (m' b))}$$

# How to model and test stateful systems?

Valid Test Sequences:

$$\sigma \models o_1 \leftarrow m_1 \iota_1; \dots; o_n \leftarrow m_n \iota_n; \operatorname{return}(P \ o_1 \cdots o_n)$$

- · ... can be generated to code
- ... can be symbolically executed ...

$$(\sigma \models ((s \leftarrow m \ \iota; m' \ s))) = False$$

$$\frac{C_m \ \iota \ \sigma}{(\sigma \models \text{return } P) = P}$$

$$\frac{C_m \ \iota \ \sigma}{(\sigma \models s \leftarrow m \ \iota; m' \ s) = (\sigma' \leftarrow (m' \ b))}$$

 $C_m \iota \sigma \qquad m \iota \sigma = None$ 

# Example: MyKeOS?

 We consider an (brutal) abstraction of an L4 Kernel IPC protocol called "MyKeOS"

#### It has

- unbounded number of tasks
- · ... having an unbounded number of threads
- ... which each have a counter for a resource
- ... the atomic actions alloc, release, status (tagged by task-id, thread-id, arguments)
- release can only release allocated ressources

# Example: MyKeOS?

• State:  $(task_id \times thread_id) \rightarrow int$ 

• Input events:

in<sub>event</sub> = alloc task\_id thread\_id nat | release task\_id thread\_id nat | status task\_id thread\_id

Output events:

out<sub>event</sub> = alloc\_ok | release\_ok | status\_ok nat

• System Model SYS: interprets input event in a state and yields an output event and a successor state if successful, an exception otherwise.

# Example: MyKeOS (0)

```
σ<sub>0</sub> ⊨ s ← mbind [ alloc tid 1 m",
release tid 0 m',
release tid 1 m'",
status tid 1] SYS;
unit(x = s)
```

# Example: MyKeOS (0)

```
\sigma_0 \vDash s \leftarrow mbind [ alloc tid 1 m'', release tid 0 m', release tid 1 m''', status tid 1] SYS; unit(x = s)
```

# Example: MyKeOS (1)

```
(tid, 1) \in dom \sigma_0 \Longrightarrow

\sigma'_0 = \sigma_0((\text{tid}, 1) \mapsto \text{the } (\sigma_0 (\text{tid}, 1)) + \text{int } m'') \Longrightarrow
```

```
σ'<sub>0</sub> ⊨ s←mbind [release tid 0 m',
release tid 1 m''',
status tid 1] SYS;
unit(x = alloc_ok # s)
```

# Example: MyKeOS (2)

```
(tid, 1) \in dom \sigma_0 \Longrightarrow

\sigma'_0 = \sigma_0((\text{tid}, 1) \mapsto \text{the } (\sigma_0 (\text{tid}, 1)) + \text{int m''}) \Longrightarrow
```

```
\sigma'_0 \vDash s \leftarrow mbind [release tid 0 m', release tid 1 m''', status tid 1] SYS; unit(x = alloc_ok # s)
```

# Example: MyKeOS (2)

```
(tid, 1) \in dom \sigma_0 \Longrightarrow
\sigma'_0 = \sigma_0((\text{tid}, 1) \mapsto \text{the } (\sigma_0 (\text{tid}, 1)) + \text{int } m'') \Longrightarrow
int m' \le \text{the } ((\sigma_0((\text{tid}, 1) \mapsto \text{the}(\sigma_0(\text{tid}, 1)) + \text{int } m''))(\text{tid}, 0)) \Longrightarrow
\sigma''_0 = \sigma'((\text{tid}, 0) \mapsto \text{the } (\sigma'(\text{tid}, 0)) - \text{int } m') \Longrightarrow
```

```
σ"<sub>0</sub> ⊨ s←mbind [release tid 1 m'",
status tid 1] SYS;
unit(x = alloc_ok # release_ok # s)
```

# Example: MyKeOS (3)

```
(tid, 1) \in dom \sigma_0 \Longrightarrow
\sigma'_0 = \sigma_0((\text{tid}, 1) \mapsto \text{the } (\sigma_0 (\text{tid}, 1)) + \text{int } m'') \Longrightarrow
int m' \le \text{the } ((\sigma_0((\text{tid}, 1) \mapsto \text{the}(\sigma_0(\text{tid}, 1)) + \text{int } m''))(\text{tid}, 0)) \Longrightarrow
\sigma''_0 = \sigma'((\text{tid}, 0) \mapsto \text{the } (\sigma'(\text{tid}, 0)) - \text{int } m') \Longrightarrow
```

```
σ"<sub>0</sub> ⊨ s←mbind [release tid 1 m'",
status tid 1] SYS;
unit(x = alloc_ok # release_ok # s)
```

# Example: MyKeOS (3)

```
(tid, 1) \in dom \ \sigma_0 \Longrightarrow 
\sigma'_0 = \sigma_0((tid, 1) \mapsto the \ (\sigma_0 \ (tid, 1)) + int \ m'') \Longrightarrow 
int \ m' \le the \ ((\sigma_0((tid, 1) \mapsto the(\sigma_0(tid, 1)) + int \ m''))(tid, 0)) \Longrightarrow 
\sigma''_0 = \sigma'((tid, 0) \mapsto the \ (\sigma'(tid, 0)) - int \ m') \Longrightarrow 
\dots \Longrightarrow \dots \Longrightarrow \dots \Longrightarrow \dots
```

```
o'''<sub>0</sub> ⊨ s←mbind [status tid 1] SYS;
unit(x = alloc_ok # release_ok # release_ok # s)
```

# Example: MyKeOS (4)

```
(tid, 1) \in dom \ \sigma_0 \Longrightarrow
\sigma'_0 = \sigma_0((tid, 1) \mapsto the \ (\sigma_0 \ (tid, 1)) + int \ m'') \Longrightarrow
int \ m' \le the \ ((\sigma_0((tid, 1) \mapsto the(\sigma_0(tid, 1)) + int \ m''))(tid, 0)) \Longrightarrow
\sigma''_0 = \sigma'((tid, 0) \mapsto the \ (\sigma'(tid, 0)) - int \ m') \Longrightarrow
... \Longrightarrow ... \Longrightarrow
\sigma'''_0 \models s \longleftarrow mbind \ [status \ tid \ 1] \ SYS;
unit(x = alloc_ok \ \# \ release_ok \ \# \ release_ok \ \# \ s)
```

# Example: MyKeOS (5)

```
 \begin{array}{l} (\text{tid}, \, 1) \in \text{dom } \sigma_0 \Longrightarrow \\ \sigma'_0 = \sigma_0((\text{tid}, \, 1) \mapsto \text{the } (\sigma_0 \, (\text{tid}, \, 1)) + \text{int m"}) \Longrightarrow \\ \text{int m'} \leq \text{the } ((\sigma_0((\text{tid}, 1) \mapsto \text{the}(\sigma_0(\text{tid}, 1)) + \text{int m"}))(\text{tid}, 0)) \Longrightarrow \\ \sigma''_0 = \sigma'((\text{tid}, \, 0) \mapsto \text{the } (\sigma'(\text{tid}, \, 0)) - \text{int m'}) \Longrightarrow \\ \ldots \Longrightarrow \ldots \Longrightarrow \ldots \Longrightarrow \ldots \Longrightarrow \\ \sigma'''_0 \vDash s \longleftarrow \text{mbind [] SYS;} \\ \text{unit}(x = \text{alloc\_ok \# release\_ok \# release\_ok \# status\_ok (\text{the}(\sigma'''_0 \, (\text{tid}, 1))) \# s) \\ \end{array}
```

# Example: MyKeOS (6)

```
 \begin{array}{l} (\text{tid, 1}) \in \text{dom } \sigma_0 \Longrightarrow \\ \sigma'_0 = \sigma_0((\text{tid, 1}) \mapsto \text{the } (\sigma_0 \ (\text{tid, 1})) + \text{int m"}) \Longrightarrow \\ \text{int m'} \leq \text{the } ((\sigma_0((\text{tid, 1}) \mapsto \text{the}(\sigma_0(\text{tid, 1})) + \text{int m"}))(\text{tid, 0})) \Longrightarrow \\ \sigma''_0 = \sigma'((\text{tid, 0}) \mapsto \text{the } (\sigma'(\text{tid, 0})) - \text{int m'}) \Longrightarrow \\ \ldots \Longrightarrow \ldots \Longrightarrow \ldots \Longrightarrow \ldots \Longrightarrow \\ \sigma'''_0 \vDash s \longleftarrow \text{mbind [] SYS;} \\ \text{unit}(x = \text{alloc\_ok \# release\_ok \# release\_ok \# status\_ok (\text{the}(\sigma'''_0 \ (\text{tid, 1}))) \# s) \\ \end{array}
```

# Example: MyKeOS (6)

```
(tid, 1) \in dom \ \sigma_0 \Longrightarrow
\sigma'_0 = \sigma_0((tid, 1) \mapsto the \ (\sigma_0 \ (tid, 1)) + int \ m'') \Longrightarrow
int \ m' \le the \ ((\sigma_0((tid, 1) \mapsto the(\sigma_0(tid, 1)) + int \ m''))(tid, 0)) \Longrightarrow
\sigma''_0 = \sigma'((tid, 0) \mapsto the \ (\sigma'(tid, 0)) - int \ m') \Longrightarrow
... \Longrightarrow ... \Longrightarrow ... \Longrightarrow
\sigma'''_0 \vDash unit(x = [alloc\_ok, release\_ok, release\_ok, status\_ok \ (the(\sigma'''_0 \ (tid, 1)))])
```

# Example: MyKeOS (7)

```
(\text{tid}, 1) \in \text{dom } \sigma_0 \Longrightarrow
\sigma'_0 = \sigma_0((\text{tid}, 1) \mapsto \text{the } (\sigma_0 (\text{tid}, 1)) + \text{int } m'') \Longrightarrow
\text{int } m' \leq \text{the } ((\sigma_0((\text{tid}, 1) \mapsto \text{the}(\sigma_0(\text{tid}, 1)) + \text{int } m''))(\text{tid}, 0)) \Longrightarrow
\sigma''_0 = \sigma'((\text{tid}, 0) \mapsto \text{the } (\sigma'(\text{tid}, 0)) - \text{int } m') \Longrightarrow
\dots \Longrightarrow \dots \Longrightarrow \dots \Longrightarrow \dots \Longrightarrow
```

```
x = [alloc_ok, release_ok, release_ok, status_ok (the(<math>\sigma'''_0 (tid,1)))])
```

# How to model and test stateful systems?

 Test Refinements for a step-function SPEC and a step function SUT:

$$\sigma \models o_1 \leftarrow \text{SPEC}_1 \ \iota_1; \dots; o_n \leftarrow \text{SPEC}_n \ \iota_n; \text{return}(res = [o_1 \cdots o_n])$$

$$\longrightarrow$$

$$\sigma \models o_1 \leftarrow \text{SUT}_1 \ \iota_1; \dots; o_n \leftarrow \text{SUT}_n \ \iota_n; \text{return}(res = [o_1 \cdots o_n])$$

 The premisse is reduced by symbolic execution to constraints over res; a constraint solver (Z3) produces an instance for res. The conclusion is compiled to a test-driver/test-oracle linked to SUT.

## Theory

 This motivates the notion of a "Generalized Monadic Test-Refinement"

```
\begin{split} (S \sqsubseteq_{\langle \Sigma_0, CC, conf \rangle} I) = \\ (\forall \ \sigma_0 \in \Sigma_0. \ \forall \ \iota s \in CC. \ \forall \ res. \\ (\sigma_0 \vDash (os \leftarrow mbind \ \iota s \ S; \ return \ (conf \ \iota s \ os \ res))) \\ \longrightarrow \\ (\sigma_0 \vDash (os \leftarrow mbind \ \iota s \ I; \ return \ (conf \ \iota s \ os \ res)))) \end{split}
```

## Theory

 This motivates the notion of a "Generalized Monadic Test-Refinement"

#### With conf set to:

- (λ is os x. length is = length os ∧ os=x)=> Inclusion Test
- (λ is os x. length is > length os ∧ os=x)
  - ==> Deadlock Refinement
- (λ is os x. length is = length os ∧ post\_cond (last os) ∧ os=x)
   => IOCO Refinement (without quiescense)

## Theory

 This motivates the notion of a "Generalized Monadic Test-Refinement"

One can now PROVE equivalences between different members of the test-refinement families

... and prove alternative forms for efficiency optimizations of the generated test-driver code.

- Assumption: Code compiled for LINUX and instrumented for debugging (gcc -d)
- Assumption: No dynamic thread creation (realistic for our target OS); identifiable atomic actions in the code;
- Assumption: Mapping from abstract atomic actions in the model to code-positions known.
- Abstract execution sequences were generated to .gdb scripts forcing explicit thread-switches of the SUT executed under gdb.

```
thread IP4_send(tid_rec, thid_rec){
      if (defined(tid_rec) &&
         defined(thid rec)) {
             grab_lock();
                atom: IPC sendinit
             release_lock();
             if(curr_tid_hasRWin_tid_rec){
                    grab_lock();
                     atom: IPC prep
                    release_lock();
             else{ return(ERROR_22);}
      else{ return(ERROR_35);}
```

```
thread IP4_receive(tid_snd, thid_snd){
      if (defined(tid_snd) &&
         defined(thid snd)) {
             grab_lock();
                atom: IPC rec rdy
             release_lock();
             if(curr_tid_hasRin_tid_rec) {
                    grab_lock();
                      atom: IPC wait
                    release_lock();
             else{ return(ERROR_59);}
      else{ return(ERROR_21);}
```

```
thread IP4_send(tid_rec, thid_rec){
      if (defined(tid_rec) &&
         defined(thid_rec)) {
"switch 2 grab_lock();
                atom: IPC sendinit
             release_lock();
             if(curr_tid_hasRWin_tid_rec){
                    grab_lock();
                     atom: IPC prep
                    release_lock();
             else{ return(ERROR_22);}
      else{ return(ERROR_35);}
```

```
thread IP4_receive(tid_snd, thid_snd){
"SWITCOTINGE(tid_snd) &&
         defined(thid_snd)) {
              grab_lock();
                 atom: IPC rec rdy
 "switch 1release_lock();
              if(curr_tid_hasRin_tid_rec) {
                      grab_lock();
                       atom: IPC wait
 "switch 1"
                      release_lock();
              else{ return(ERROR_59);}
       else{ return(ERROR_21);}
```

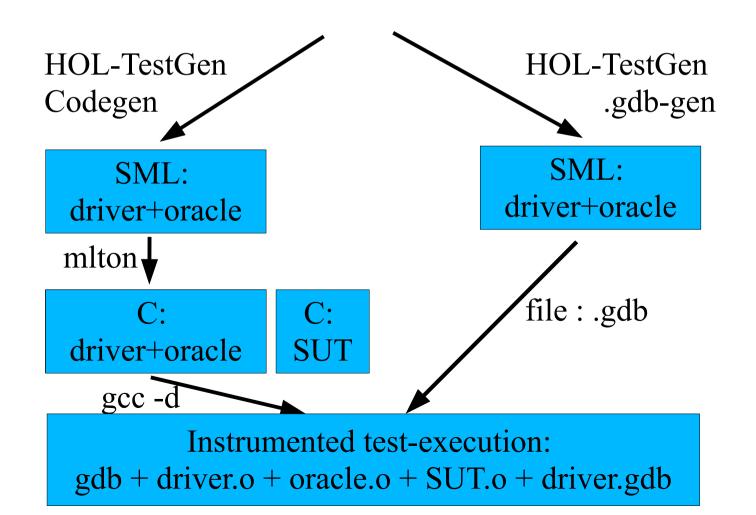
```
thread IP4_send(tid_rec, thid_rec){
      if (defined(tid_rec) &&
         defined(thid_rec)) {
"switch 2" grab_lock():
               atom: IPC senami
             release_bck();
             if(curr_tid_hasRWin_tid_rec){
                    grab_lock();
                      tom: IPC prep
                    release_lock();
             else{ return(ERROR_22);}
      else{ return(ERROR_35);}
```

```
thread IP4_receive(tid_snd, thid_snd){
"SWITCAfined(tid_snd) &&
         defined(th d_snd)) {
              grab_lock();
                 atom: IPC rec rdy
 "switch 1release_lock();
              if(curr_tid_hasRin_tid_rec) {
                   grab_lock();
                      atom: IPC wait
 "switch 1"
                   release_lock();
              else{ return(ERROR_59);}
       else{ return(ERROR_21);}
```

 Computing the input sequence as interleaving of atomic actions of system-API-Calls:

where ı<sub>j</sub>

$$\sigma \models o_1 \leftarrow \text{SUT}_1 \ \iota_1; \dots; o_n \leftarrow \text{SUT}_n \ \iota_n; \text{return}(res = [o_1 \cdots o_n])$$



## Conclusion

Monadic approach to sequence testing:

- 1. no surrender to finitism and constructivism
- 2. sensible shift from syntax to semantics: computations + compositions, not nodes + arcs
- 3. explicit difference between input and output,
- 4. theoretical and practical framework of numerous conformance notions,
- 5. new ways to new calculi of symbolic evaluation

## Conclusion

Testing Bank: a protocol with 3 operations ...

- 1. Optimized split + prune essential.
- 2. Symbolic execution can be effectively realised with e-matching.
- 3. 10<sup>8</sup> protocol-load IS FEASABLE in Isabelle ...
- 4. ... in a well-designed symbolic execution process, the computation load is in the normalization(but this can be highly parallelized)

## Conclusion

HOL-TestGen is an Advanced Model-based
 Testing Environment built on top of Isabelle/HOL

 Allows to establish a Link between a formal System Model in Isabelle/HOL and Real Code by (semi)-automated generation of tests.

Smooth Integration of Test and Proof!